

# Term Inference in Dedukti

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$\lambda$ -calculus:

$$\lambda x y.x$$

With simple types:

$$\vdash \lambda x y.x : A \rightarrow B \rightarrow A$$

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$\lambda\Pi$ -calculus modulo:

Declare  $(n + m) + p \equiv n + (m + p)$  then with

$$\text{append} : \forall n \ m. \text{vector } n \rightarrow \text{vector } m \rightarrow \text{vector } (n + m)$$

the following have the same type:

$$\text{append } (n + m) \ p \ (\text{append } n \ m \ a \ b) \ c : \text{vector } ((n + m) + p)$$

$$\text{append } n \ (m + p) \ a \ (\text{append } m \ p \ b \ c) : \text{vector } (n + (m + p))$$

Conversion:

$$\text{vector } ((n + m) + p) \equiv? \text{vector } (n + (m + p))$$

Unification:

$$\text{vector } (\_ + p) \equiv? \text{vector } ((n + m) + \_)$$

Inference:

$$\text{append } \_ \_ a \text{ nil} : \_$$

becomes

$$\text{append } n \ 0 \ a \ \text{nil} : \text{vector } (n + 0)$$

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- Simple types: all decidable.
- Dependent types: unification undecidable, type inference decidable with annotations ( $\lambda x : A. t$ ).
- Goal: investigate separation of concerns in inference algorithms, through adding one to Dedukti.

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Conclusion

$$\overline{\Gamma \vdash \text{Type} : \text{Kind}}$$

$$\frac{x : A \in \Gamma}{\Gamma \vdash x : A}$$

$$\frac{c : A \in \Sigma}{\Gamma \vdash c : A}$$

$$\frac{\Gamma \vdash t : T \quad T \triangleright \Pi x : A. B \quad \Gamma \vdash u : A}{\Gamma \vdash t u : B[x \leftarrow u]}$$

$$\frac{\Gamma \vdash A : \text{Type} \quad \Gamma, x : A \vdash t : B \quad B \neq \text{Kind}}{\Gamma \vdash \lambda x : A. t : \Pi x : A. B}$$

$$\frac{\Gamma \vdash A : \text{Type} \quad \Gamma, x : A \vdash B : s}{\Gamma \vdash \Pi x : A. B : s}$$

$$\frac{\Gamma \vdash t : A \quad \Gamma \vdash B : s \quad A \equiv B}{\Gamma \vdash t : B}$$



```
type 'a t
val return : 'a -> 'a t
val (>>=) : 'a t -> ('a -> 'b t) -> 'b t
val run : 'a t -> 'a
```

Operations:

```
val get : state t  
val set : state -> unit t  
  
val plus : 'a t list -> 'a t  
val fail : 'a t
```

Example:

```
set 1 >>= fun () ->  
plus  
[ set 0 >>= fun () -> fail  
; get >>= fun n -> print n ]
```

## Definition (Partial terms)

Partial terms are terms where subterms can be the placeholder term `_`.

Examples:

- $\lambda x : \_ . x$  an identity function for some type left to be inferred.
- $(\lambda x : \_ . x x) (\lambda x : \_ . x x)$  the classical bad term.
- *plus* `_ 1 0` a use case for a polymorphic group operator  
 $plus : \prod(G : group). gtype\ G \rightarrow gtype\ G \rightarrow gtype\ G.$

## Definition (Extended terms)

Extended terms are terms where subterms may be

- a metavariable  $?_i[\sigma]$  where  $?_i$  is its name and  $\sigma = [x_1 \leftarrow t_1, \dots, x_n \leftarrow t_n]$  a substitution.
- a guarded term  $p[\sigma] t$  where  $p$  is its name,  $\sigma$  a substitution and  $t$  an extended term.

Metavariables are placeholders with additional information.

Guards are used for typing to deal with constraints.

Elaboration is the process taking a partial term and

- replacing placeholders with metavariables
- generating unification constraints attached to guards
- generating a prospective type (which is an extended term)

Judgements:

$$\Gamma \vdash t \uparrow u : T$$

$$\Gamma \vdash t : T \downarrow u$$

In pseudocode they're monadic functions

```
val infer : context -> partial term ->  
  (extended term * extended term) t  
val check : context -> partial term ->  
  extended term -> extended term t
```

The monad provides a state  $\Theta$  (unification problem), with information about metavariables and guards, with backtracking.

Translate the typing rules:

$$\frac{x : A \in \Gamma}{\Gamma \vdash x \uparrow x : A}$$

$$\overline{\Gamma \vdash \text{Type} \uparrow \text{Type} : \text{Kind}}$$

$$\frac{c : A \in \Sigma}{\Gamma \vdash c \uparrow c : A}$$

$$\frac{\Gamma \vdash a : \text{Type} \Downarrow A \quad \Gamma, x : A \vdash t \uparrow u : B \quad B \neq \text{Kind}}{\Gamma \vdash \lambda x : a.t \uparrow \lambda x : A.u : \Pi x : A.B}$$

$$\frac{\Gamma \vdash a : \text{Type} \Downarrow A \quad \Gamma, x : A \vdash b \uparrow B : s \quad s \text{ sort}}{\Gamma \vdash \Pi x : a.b \uparrow \Pi x : A.B : s}$$

$$\frac{\Gamma \vdash f \uparrow g : T \quad T \triangleright \Pi x : A.B \quad \Gamma \vdash t : A \Downarrow u}{\Gamma \vdash f t \uparrow g u : B[x \leftarrow u]}$$

$$\frac{\Gamma \vdash f \uparrow g : T \quad T \triangleright \Pi x : A. B \quad \Gamma \vdash t : A \Downarrow u}{\Gamma \vdash f t \uparrow g u : B[x \leftarrow u]}$$

In pseudocode:

```
let infer ctx (f t) = infer ctx f >>= fun (g,T) ->
  whnf T >>= function
  | Pi (x:A) B -> check ctx t A >>= fun u ->
    return ((g u), B[x <- u])
  | _ -> fail
```

Guards let us translate the conversion rule into an elaboration rule:

$$\frac{\Gamma \vdash t \uparrow t' : A \quad \text{NewGuard}(\Gamma \vdash p : A \rightarrow B)}{\Gamma \vdash t : B \downarrow p[id_{\Gamma}] t'}$$



Placeholders become metavariables:

$$\frac{\text{NewMeta}(\Gamma \vdash ?_j : *) \quad \text{NewMeta}(\Gamma \vdash ?_i : ?_j[id_\Gamma])}{\Gamma \vdash \_ \uparrow ?_i[id_\Gamma] : ?_j[id_\Gamma]}$$

In pseudocode:

```
let infer ctx _ = new_meta ctx MType >>= fun mty ->
  new_meta ctx (MTyped mty) >>= fun m ->
  return (m, mty)
```

## Definition

A unification problem is given by

- metavariable declarations  $\Gamma \vdash ?_i : T$  (also type metavariable and sort metavariable versions)
- guard declarations  $\Gamma \vdash p : A \rightarrow B$  each associated with a list of constraints  $\Delta \vdash t \equiv u$
- metavariable definitions  $?_i := t$

Guards are pass-through when they have no associated constraints:

$$p[\sigma] t \equiv t.$$

Metavariables are convertible with their definitions:  $?_i[\sigma] \equiv \sigma(t)$  when  $?_i := t$ .

Adding to the problem:

- *NewMeta*( $\Gamma \vdash ?_i : T$ ) when  $\Gamma \vdash T : *$  (also type metavariable and sort metavariable versions).
- *NewGuard*( $\Gamma \vdash p : A \rightarrow B$ ) when  $A$  and  $B$  are types or sorts under  $\Gamma$ , with initial constraint list  $[\Gamma \vdash A \equiv B]$ .
- *Define*( $?_i := t$ ) when  $?_i$  is declared as  $\Gamma \vdash ?_i : T$  without a definition and  $\Gamma \vdash t : T$ ,  
AND occurs check: no defining  $?_i := ?_j + ?_k$  and  $?_j := ?_i$ .

Refinement:

- *Narrow*( $?_i, \Delta$ ): when  $\Gamma \vdash ?_i : T$  declared not defined, and  $\Delta \subseteq \Gamma$  such that  $\exists \Delta', \Delta' \subseteq \Delta$  and  $\Delta' \vdash T : *$ ,  
*NewMeta*( $\Delta' \vdash ?_j : T$ ) then *Define*( $?_i := ?_j[id_{\Delta'}]$ ).
- *Refine*( $?_i := t$ ): when  $\Gamma \vdash ?_i : B$  declared not defined and  $\Gamma \vdash t : A$ ,  
*NewGuard*( $\Gamma \vdash p : A \rightarrow B$ ) then *Define*( $?_i := p[id_{\Gamma}] t$ ).

Transform constraints:

- $\Gamma \vdash A \equiv B$  when  $A \equiv B$ : can be removed.
- $\Gamma \vdash A \equiv B$  with  $A \triangleright A'$  and  $B \triangleright B'$ : can be replaced with  $\Gamma \vdash A' \equiv B'$ .
- $\Gamma \vdash \lambda x : A. t \equiv \lambda y : B. u$ : can be replaced with  $\Gamma \vdash A \equiv B$  AND  $\Gamma, x : A \vdash t \equiv u[y \leftarrow x]$ .
- as above with  $\Pi$  and applications.

```
val get_constraint : constraint t
val refine : meta -> extended term -> unit t
val constraint_solved : unit t
```

```
let trivial_rule = function
| ctx, ?i [] == t -> refine ?i t
| _ -> fail
```

```
let rec solve = get_constraint >>= function
| Some c -> plus
  [ constraint_solved
  ; (trivial_rule c)
  ; ... ] >>= fun () ->
  solve
| None -> return ()
```

Some rules:

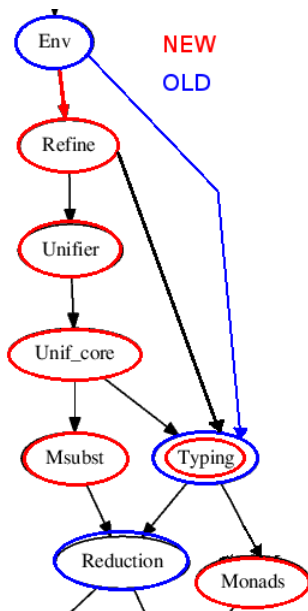
$$\frac{\Gamma \vdash t \equiv u \quad \Gamma \vdash t_1 \equiv u_1 \quad \dots \quad \Gamma \vdash t_n \equiv u_n}{\Gamma \vdash t \ t_1 \dots t_n \equiv u \ u_1 \dots u_n}$$

$$\frac{\text{Narrow}(?_i, \{x, \sigma(x) = \rho(x)\})}{\Gamma \vdash ?_i[\sigma] \equiv ?_i[\rho]}$$

$$\frac{\sigma \text{ invertible} \quad \text{Refine}(?_i, \sigma^{-1}(t))}{\Gamma \vdash ?_i[\sigma] \equiv t}$$

(other rules not displayed)

Rules adapted from Beta Ziliani and Matthieu Sozeau, *A Predictable Unification Algorithm for Coq Featuring Universe Polymorphism and Overloading*





- Separation of concern embodied
  - in the theory: elaboration / safe primitives / heuristics
  - in the code: only safe interfaces exported
- Experimental validation:

```
transport (A : _) (P : _)
  (x : U A) (y : _) (e : _)
  (H : U (P x)) : U (P y)
:= eq_rect _ x (a : _ => p : _ => P a) H _ e.
```

Possible termination bug to investigate.

- Future work:
  - placeholders on the left hand side of a rewrite rule:  $P \_ \longrightarrow t$
  - high level features: implicit arguments, coercions, user provided unification hints, etc.